

Chapter 17 Second-Order Differential Equations

17.1 Second-Order Linear Equation (page 1154)

A *second-order linear differential equation* (二階線性微分方程) has the form

$$P(x)\frac{d^2y}{dx^2} + Q(x)\frac{dy}{dx} + R(x)y(x) = G(x), \quad (1)$$

where $P, Q, R,$ and G are continuous functions.

Definition 1 (page 1154).

- (a) If $G(x) = 0$ for all x , we say (1) *homogeneous linear equations* (齊次線性方程).
- (b) If $G(x) \neq 0$ for some x , we say (1) *nonhomogeneous linear equations* (非齊次線性方程).

In this section, we will focus on the solutions of the homogeneous linear equation:

$$P(x)\frac{d^2y}{dx^2} + Q(x)\frac{dy}{dx} + R(x)y(x) = 0. \quad (2)$$

Theorem 1 (page 1154). *If $y_1(x)$ and $y_2(x)$ are both solutions of the linear homogeneous equation (2) and c_1 and c_2 are any constants, then the function $y(x) = c_1y_1(x) + c_2y_2(x)$ is also a solution of Equation (2).*

Proof. For $i = 1, 2$, we have $P(x)y_i'' + Q(x)y_i' + R(x)y_i = 0$. So

$$\begin{aligned} & P(x)y'' + Q(x)y' + R(x)y \\ &= P(x)(c_1y_1 + c_2y_2)'' + Q(x)(c_1y_1 + c_2y_2)' + R(x)(c_1y_1 + c_2y_2) \\ &= P(x)(c_1y_1'' + c_2y_2'') + Q(x)(c_1y_1' + c_2y_2') + R(x)(c_1y_1 + c_2y_2) \\ &= c_1(P(x)y_1'' + Q(x)y_1' + R(x)y_1) + c_2(P(x)y_2'' + Q(x)y_2' + R(x)y_2) \\ &= c_1 \cdot 0 + c_2 \cdot 0 = 0. \end{aligned}$$

□

Definition 2 (page 1155). Two continuous functions y_1 and y_2 are called *linearly independent* (線性獨立) if neither y_1 nor y_2 is a constant multiple of the other.

Theorem 2 (page 1155). *If y_1 and y_2 are linearly independent solutions of (2) on an interval, and $P(x)$ is never 0, then the general solution is given by $y(x) = c_1y_1(x) + c_2y_2(x)$, where c_1 and c_2 are arbitrary constants.*

Here we will discuss the second-order homogeneous linear differential equation with constant coefficients, that is $P, Q,$ and R are constant functions. In this case, we write the differential equation as

$$ay''(x) + by' + cy(x) = 0, \quad (3)$$

where $a, b,$ and c are constants and $a \neq 0$.

Consider $y = e^{rx}$, where r is a constant, then $y' = re^{rx}$ and $y'' = r^2e^{rx}$. So

$$ar^2e^{rx} + bre^{rx} + ce^{rx} = 0 \Rightarrow (ar^2 + br + c)e^{rx} = 0 \Rightarrow ar^2 + br + c = 0.$$

Thus $y = e^{rx}$ is a solution of (3) if r is a root of

$$ar^2 + br + c = 0. \quad (4)$$

Equation (4) is called the *auxiliary equation* (or *characteristic equation*) (輔助方程、特徵方程) of the differential equation $ay'' + by' + cy = 0$.

There are three cases for the roots of the equation (4).

- (1) If $b^2 - 4ac > 0$, then $r_1 = \frac{-b + \sqrt{b^2 - 4ac}}{2a}$ and $r_2 = \frac{-b - \sqrt{b^2 - 4ac}}{2a}$ are two real distinct roots. So $y_1 = e^{r_1x}$ and $y_2 = e^{r_2x}$ are two linearly independent solutions. Hence the general solution of $ay'' + by' + cy = 0$ is $y = c_1e^{r_1x} + c_2e^{r_2x}$.
- (2) If $b^2 - 4ac = 0$, then $r_1 = r_2 = -\frac{b}{2a}$ are two real double roots. Here we denote the double roots by r . So $y_1 = e^{rx}$ is a solution of $ay'' + by' + cy = 0$. To find another solution y_2 which is linearly independent of y_1 , we consider the method of *reduction of order* (降階法). Let $y_2 = u(x)y_1(x)$, where $u(x) \neq$ constant function, be another solution of $ay'' + by' + cy = 0$. Since

$$\begin{aligned} c \cdot y_2 &= c \cdot uy_1 \\ b \cdot y_2' &= b \cdot (u'y_1 + uy_1') \\ a \cdot y_2'' &= a \cdot (u''y_1 + 2u'y_1' + uy_1''), \end{aligned}$$

we have

$$ay_2'' + by_2' + cy_2 = au''y_1 + u'(2ay_1' + by_1) + u(ay_1'' + by_1' + cy_1) = au''y_1 = 0,$$

and it implies $u''(x) = 0$, $u'(x) = C_1$, and $u(x) = C_1x + C_2$. In particular, $u(x) = x$ is a candidate, and the general solution of solution of $ay'' + by' + cy = 0$ is $y = c_1e^{rx} + c_2xe^{rx}$.

(3) If $b^2 - 4ac \leq 0$, then $r_1 = \frac{-b + \sqrt{4ac - b^2}i}{2a}$ and $r_2 = \frac{-b - \sqrt{4ac - b^2}i}{2a}$ are two conjugate complex roots. Denote $\alpha = -\frac{b}{2a}$ and $\beta = \frac{\sqrt{4ac - b^2}}{2a}$. When we consider the equation and solution in the complex sense, which is an algebraically closed field, we write the solution of the differential equation as

$$\begin{aligned} y &= C_1 e^{r_1 x} + C_2 e^{r_2 x} = C_1 e^{(\alpha + \beta i)x} + C_2 e^{(\alpha - \beta i)x} \\ &= C_1 e^{\alpha x} (\cos \beta x + i \sin \beta x) + C_2 e^{\alpha x} (\cos(-\beta x) + i \sin(-\beta x)) \\ &= (C_1 + C_2) e^{\alpha x} \cos \beta x + i(C_1 - C_2) e^{\alpha x} \sin \beta x \end{aligned}$$

The solution is real if and only if $c_1 = C_1 + C_2$ and $c_2 = i(C_1 - C_2)$ are real numbers, that is, $y = e^{\alpha x}(c_1 \cos \beta x + c_2 \sin \beta x)$ is the general solution.

Initial-Value and Boundary-Value Problems, page 1158

An *initial-value problem* (初始值問題) for the second-order linear equation consists of finding a solution y of the differential equation that also satisfies initial conditions of the form $y(x_0) = y_0, y'(x_0) = y_1$, where y_0 and y_1 are given constants. If P, Q, R , and G are continuous on an interval and $P(x) \neq 0$ there, then a theorem guarantees the existence and uniqueness of a solution to this initial-value problem.

A *boundary-value problem* (邊界值問題) for the second-order linear equation consists of finding a solution y of the differential equation that also satisfies boundary conditions of the form $y(x_0) = y_0, y(x_1) = y_1$. In contrast with the situation for initial-value problems, a boundary-value problem does *not* always have a solution.

Example 1 (page 1156, 1158). Solve the initial value problem $y'' + y' - 6y = 0$, $y(0) = 1$ and $y'(0) = 1$.

Solution.

Example 2 (page 1157). Solve the boundary value problem $y'' + 2y' + y = 0$, $y(0) = 1, y(1) = 3$.

Solution.

Example 3 (page 1158). Solve the equation $y'' - 6y' + 13y = 0$.

Solution.

Example 4 (page 1158). Solve the initial-value problem $y'' + y = 0$, $y(0) = 2$, $y'(0) = 3$.

Solution.

Example 5. We can view $ay'' + by' + cy = 0$ as $(\frac{d}{dx} + r_1)(\frac{d}{dx} + r_2)y = 0$, where r_1 and r_2 are two roots of the corresponding characteristic equation. Let $Y = (\frac{d}{dx} + r_2)y$. Then we can solve $(\frac{d}{dx} + r_1)Y = 0$, and then we solve $(\frac{d}{dx} + r_2)y = Y$ by the integrating factor method. In this case, you will easily see that the solutions are “2-dimensional”.